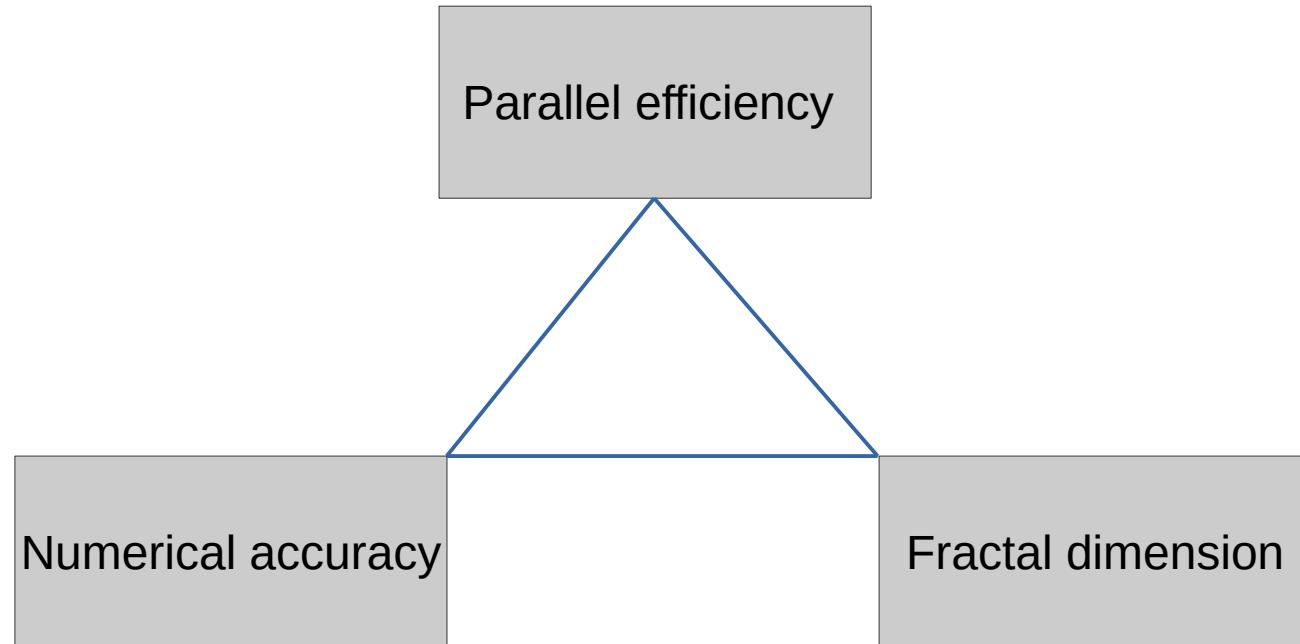


How to Converge on a Tree Grid?

Antoon van Hooft
BGUM 2023, Paris
In collaboration with:
Stephane Popinet

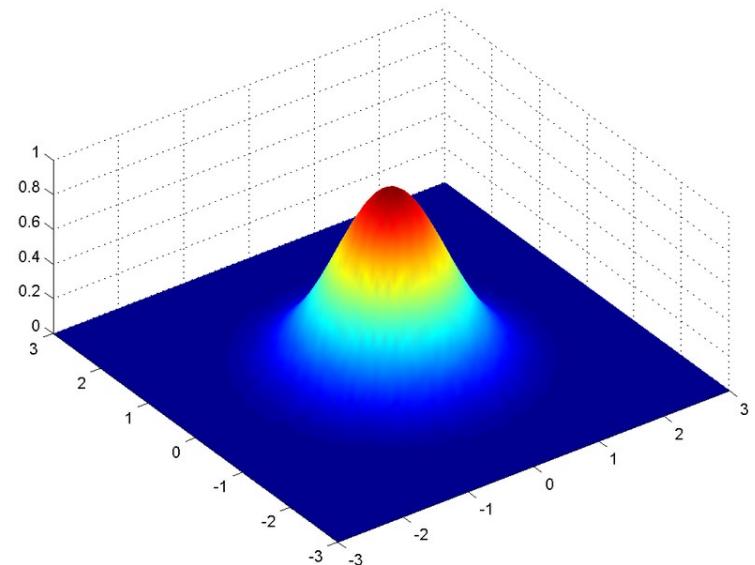
The Weak Scaling Triad of High-Performance Computing



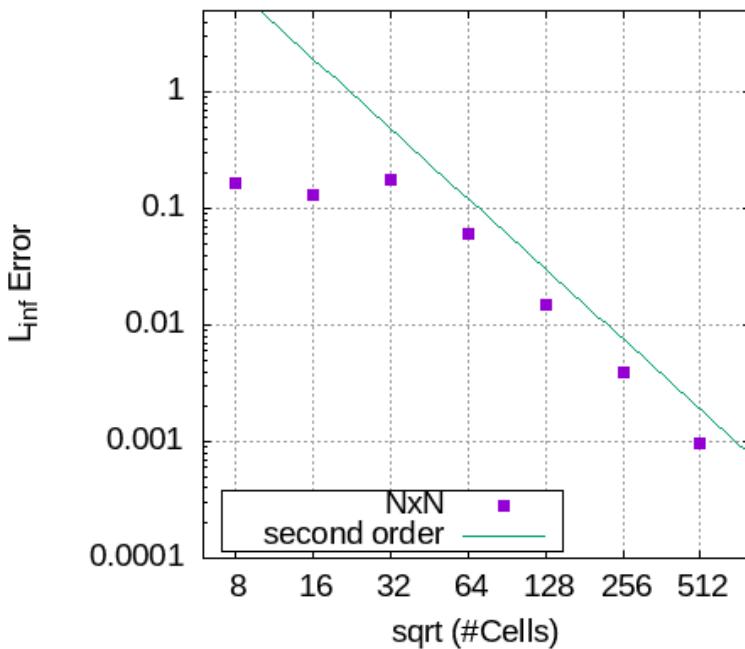
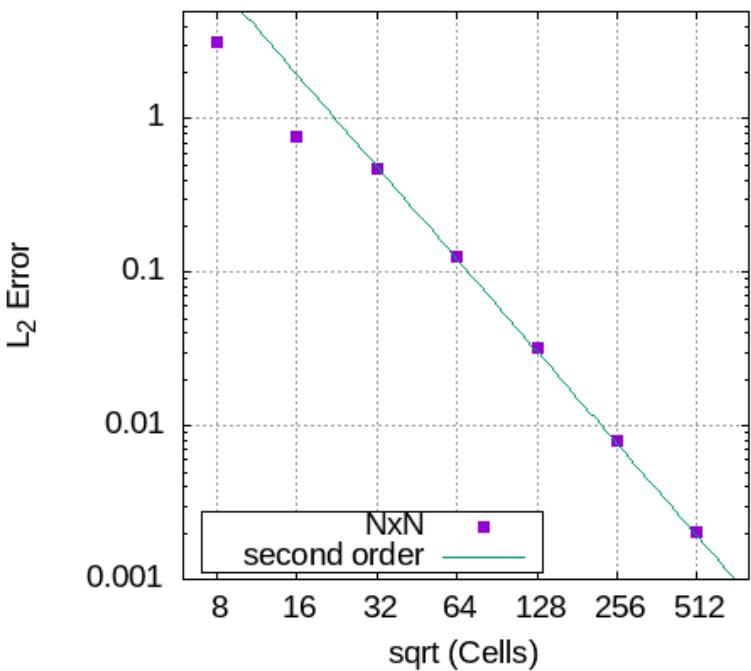
An example

$$\frac{\partial s}{\partial t} = \nabla^2 s$$

$$s(x, y) = e^{-x^2 - y^2}$$



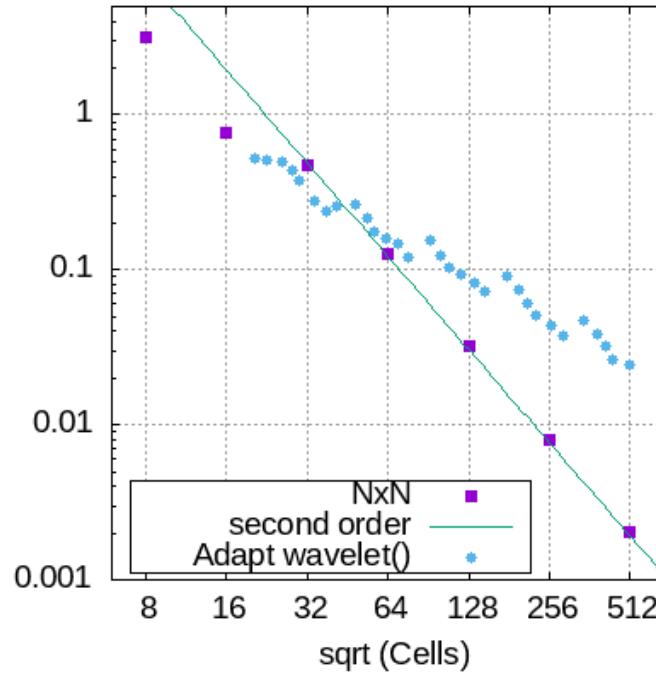
An example; Equidistant grid



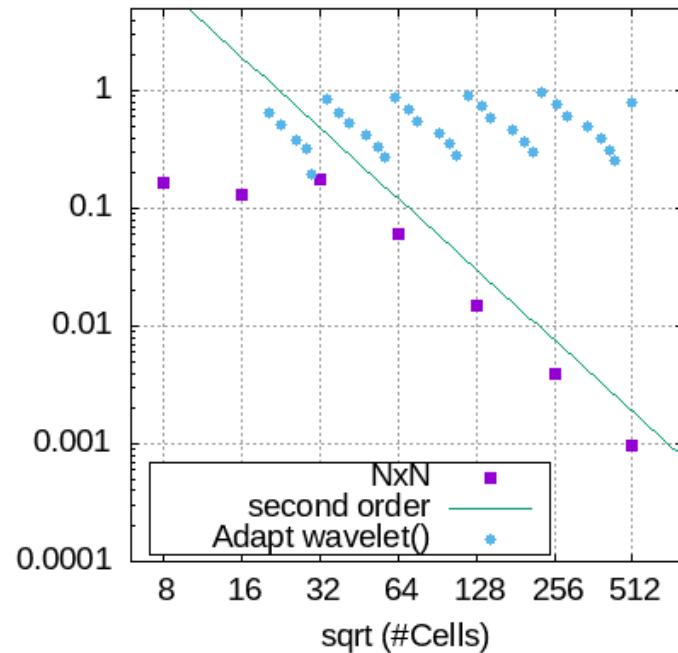
See; www.basilisk.fr/sandbox/antoonvh/diffusion_error.c

An example; Adaptive grid

• • •



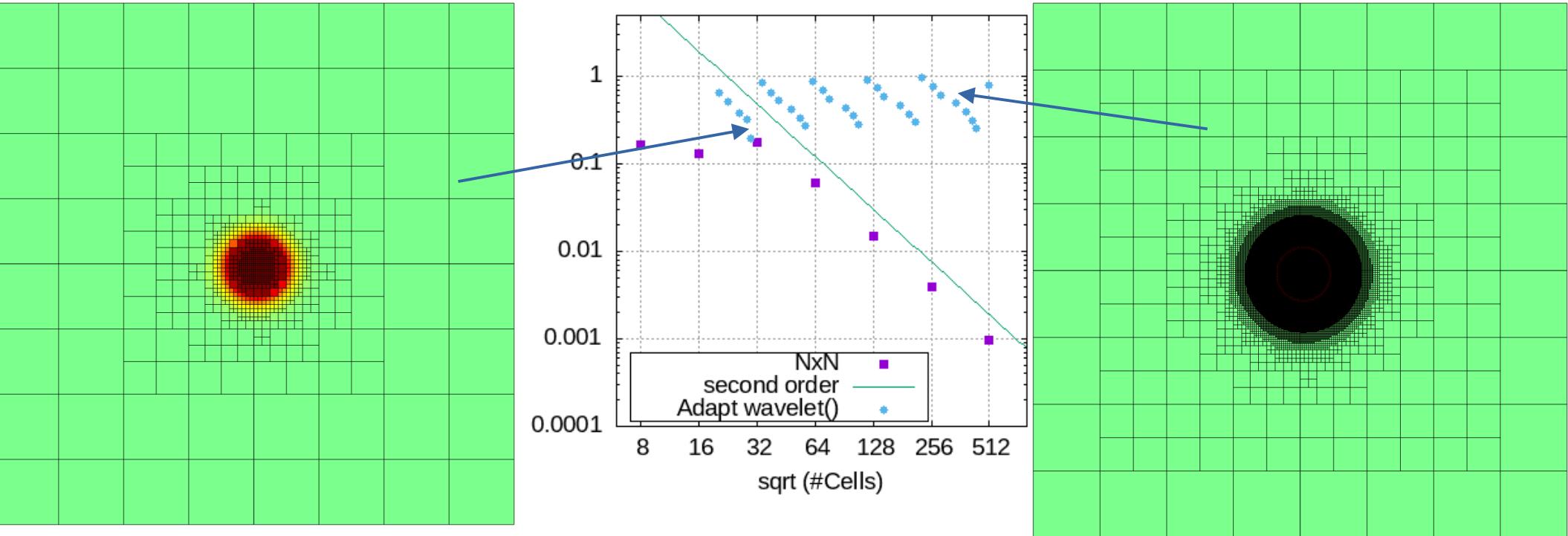
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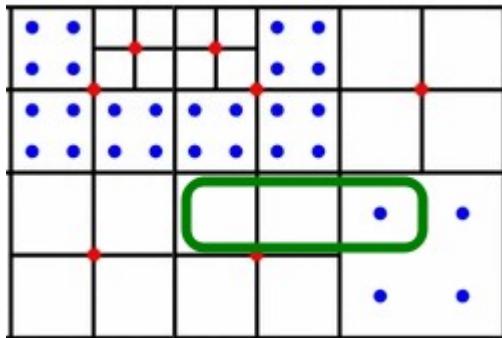
See; www.basilisk.fr/sandbox/antoonvh/diffusion_error.c

An example; Adaptive grid



See; www.basilisk.fr/sandbox/antoonvh/diffusion_error.c

An example; Adaptive grid

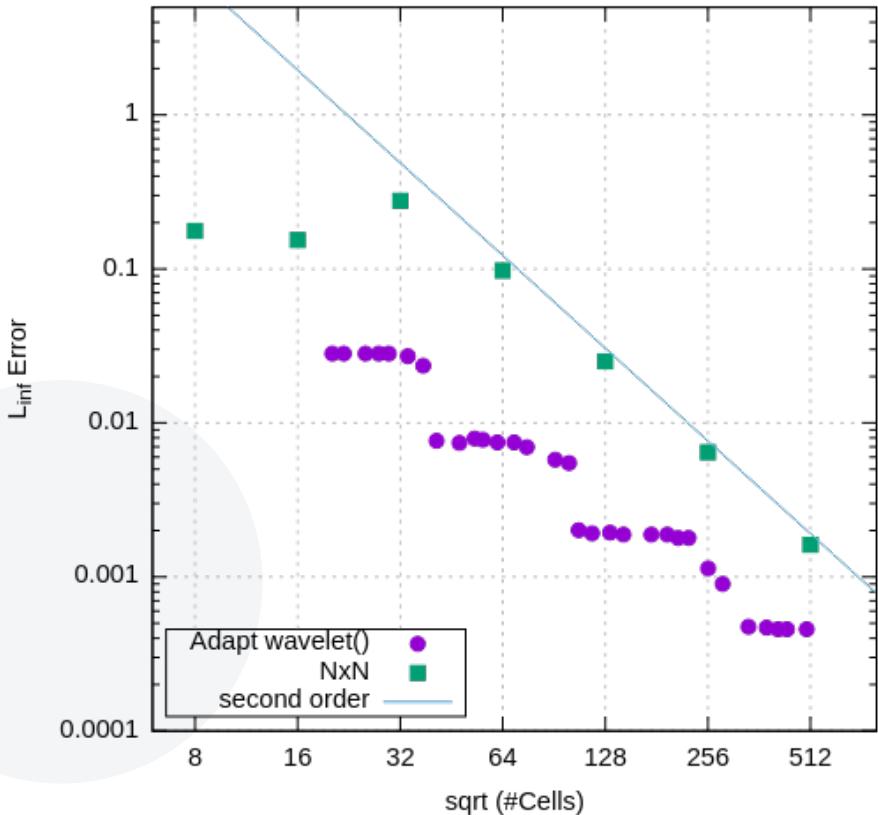


$$\frac{\partial^2 s}{\partial x^2} \approx \frac{s[-1] - 2s[] + s[1]}{\Delta^2} =$$

$$= \frac{s[-1] - 2s[] + s_e[1] + \epsilon \Delta^2}{\Delta^2} =$$

$$= \frac{s[-1] - 2s[] + s_e[1]}{\Delta^2} + \epsilon$$

An example; Adaptive grid



$$s[1] = s_e[1] + \xi \Delta^4$$

```
#include "higher-order.h"
```

```
s.prolongation = refine_4th;
```

See; www.basilisk.fr/sandbox/antoonvh/diffusion_error_fix.c

Higher-order methods? Recall BGUM 2017...



Sorbonne Université

École Doctorale Sciences Mécaniques, Acoustique, Électronique & Robotique
Institut Jean Le Rond d'Alembert (∂ 'Alembert UMR 7190)
Laboratoire d'Informatique de Paris 6 (LIP6 UMR CNRS 7606)

Higher-order adaptive methods for fluid dynamics

By M. Rajarshi Roy Chowdhury
PhD thesis on Fluid Mechanics
Co-directed by M. Stéphane Popinet & M. Stef Graillat

Thesis Defense on 30 November, 2018
Before a jury composed of

Bolse State University, USA
Université de Toulon, France
Université Paris-Est-Marne-La-Vallée, France
Sorbonne Université, France
Sorbonne Université, France
Sorbonne Université, France

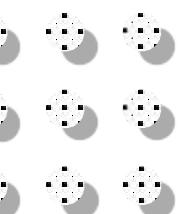
Rapporteuse
Rapporteur
Examinateur
Examinateur

Mme. Donna Calhoun
M. Frédéric Golay
M. Stéphane Vincent
M. Ivan Delbende
M. Stef Graillat
M. Stéphane Popinet

A fourth-order accurate adaptive solver for
incompressible flow problems?

$$\frac{\partial \mathbf{u}}{\partial t} = -(\mathbf{u} \cdot \nabla) \mathbf{u} - \nabla p + \nu \nabla^2 \mathbf{u} + \mathbf{a},$$

$$\nabla \cdot \mathbf{u} = 0.$$



A fourth-order accurate adaptive solver for incompressible flow problems?

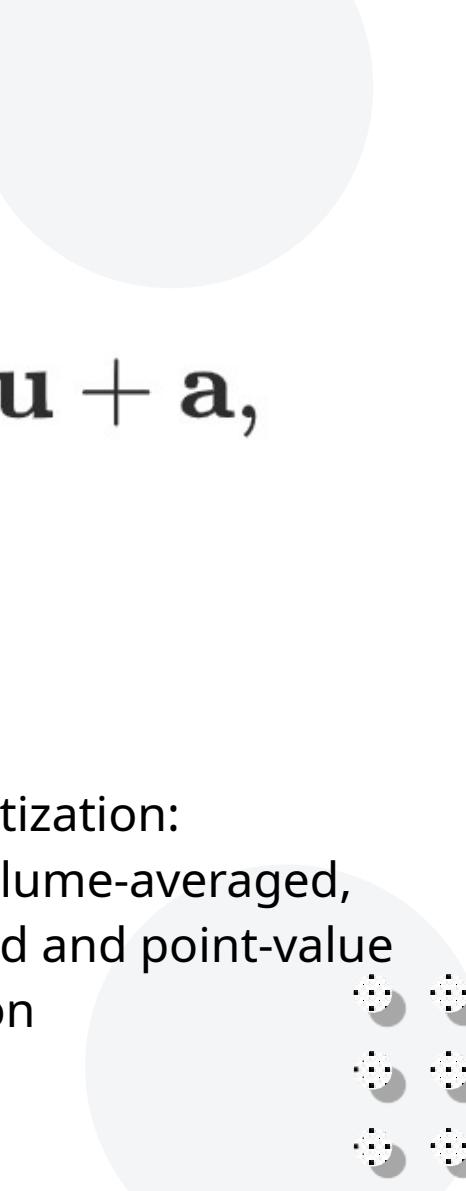
$$\frac{\partial \mathbf{u}}{\partial t} = -(\mathbf{u} \cdot \nabla) \mathbf{u} - \nabla p + \nu \nabla^2 \mathbf{u} + \mathbf{a},$$

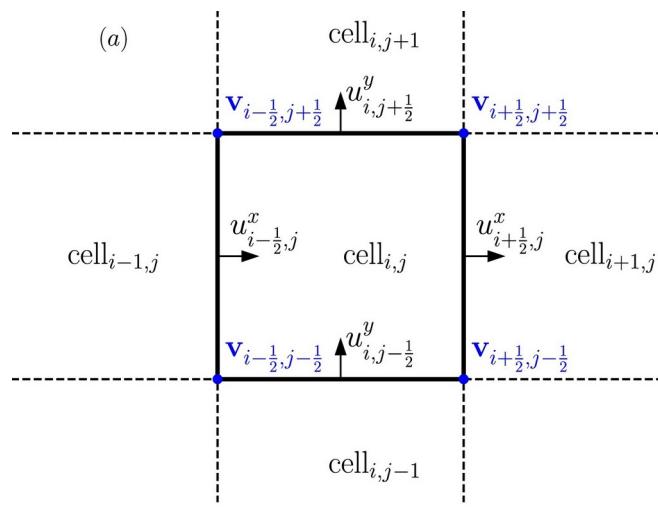
$$\nabla \cdot \mathbf{u} = 0.$$

Time integrator:
4th-order accurate
Runge-Kutta scheme

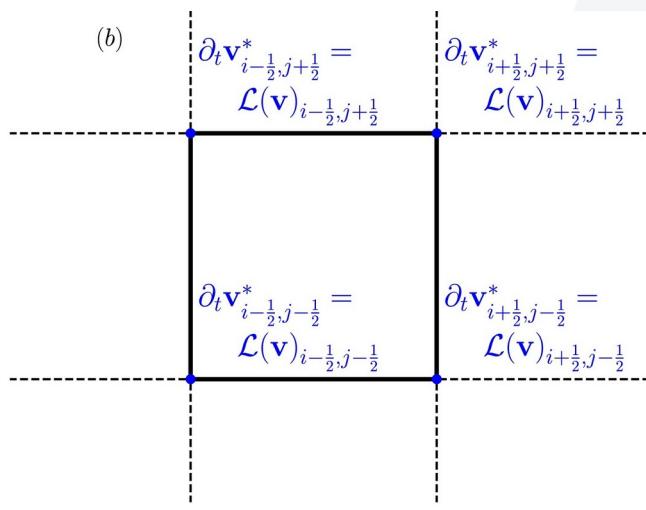
$$\frac{\partial \mathbf{u}}{\partial t} = \mathcal{L} (\mathbf{u})$$

Spatial discretization:
Combined volume-averaged,
Face-averaged and point-value
representation

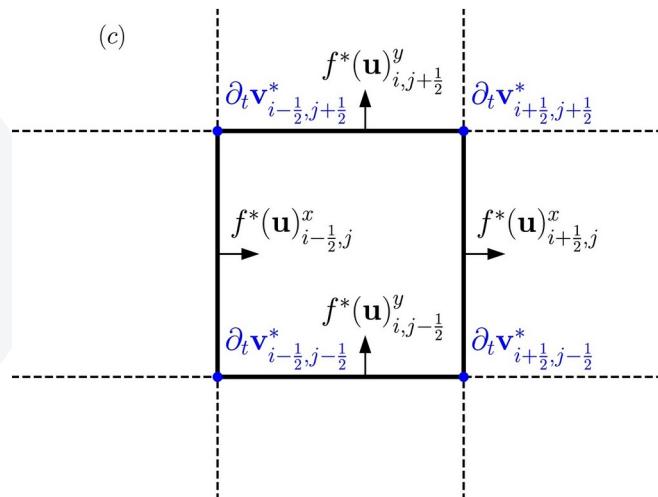




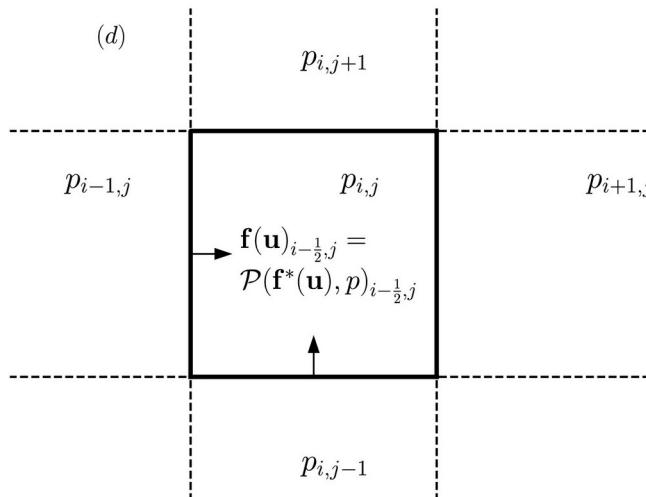
(a) Interpolation of the face-averaged velocities (black) to vertex-point values (blue)



(b) Computation of the provisional tendency vector field at the vertex locations



(c) Interpolation of the provisional tendency from the vertex-point values to face-averaged values.



(d) The (global) solenoidal projection (\mathcal{P}) of the provisional tendency using the scalar field p

Advection term requires gradients:

4-th-order accurate central difference:

$$s'[] = \frac{1}{12\Delta} (s[-2] - 8s[-1] + 8s[] - s[2]) + \epsilon\Delta^4$$

cf. 4-th-order accurate *compact upwind* scheme:

$$\begin{aligned} s'[] - \frac{76}{197}s'[1] + \frac{17}{197}s'[2] = \\ \frac{1}{197\Delta} (27s[-2] - 192s[-1] + 165s[]) + \epsilon\Delta^4 \end{aligned}$$

Higher-order adaptive refinement

$$\Xi_i = \chi_i$$

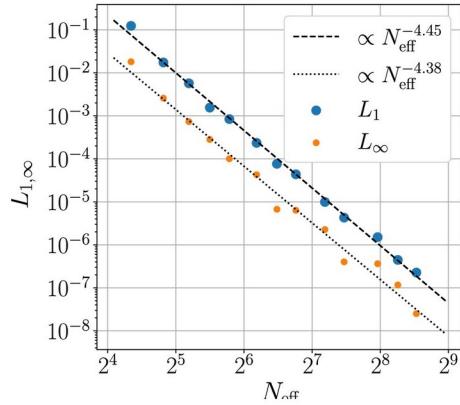
Refinement indicator Ξ_i Wavelet-based estimated error
i.e. "prolongation error"

$$\Xi_i = \Delta^k \chi_{i,\max \text{ of siblings}}$$

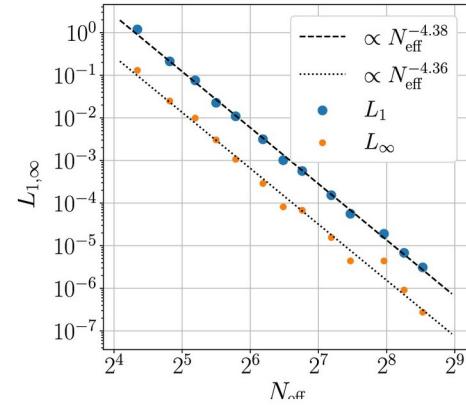
Refinement "penalty" ($k > 0$)

Test: 1) Adaptive convergence for a Gaussian vortex

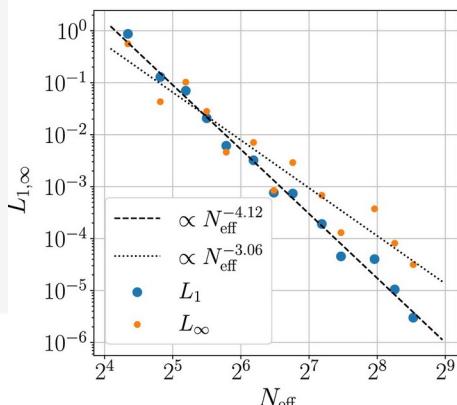
(a) Face average to vertex



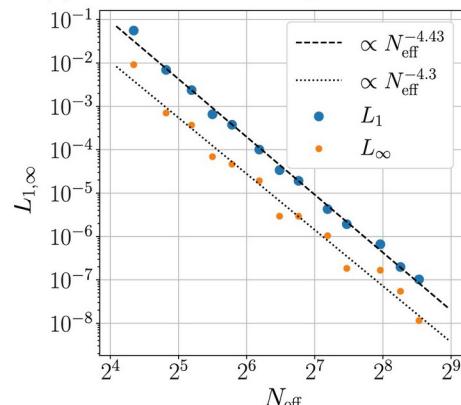
(b) First derivative at vertices



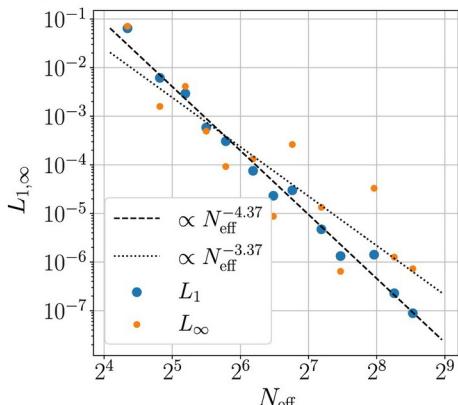
(c) Second derivative



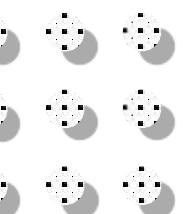
(d) Vertex to face average



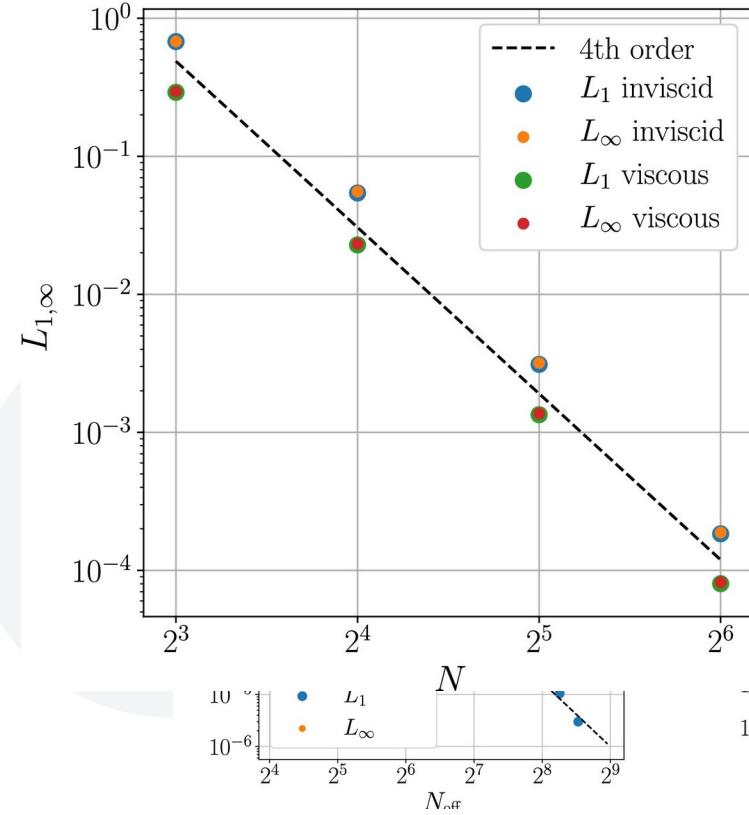
(e) First derivative on faces



Test: 2) Taylor-Green vortex



(a) $\mathbf{u}(t = 2)$



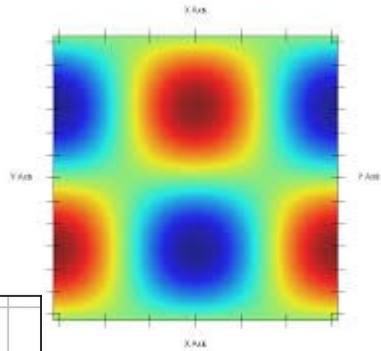
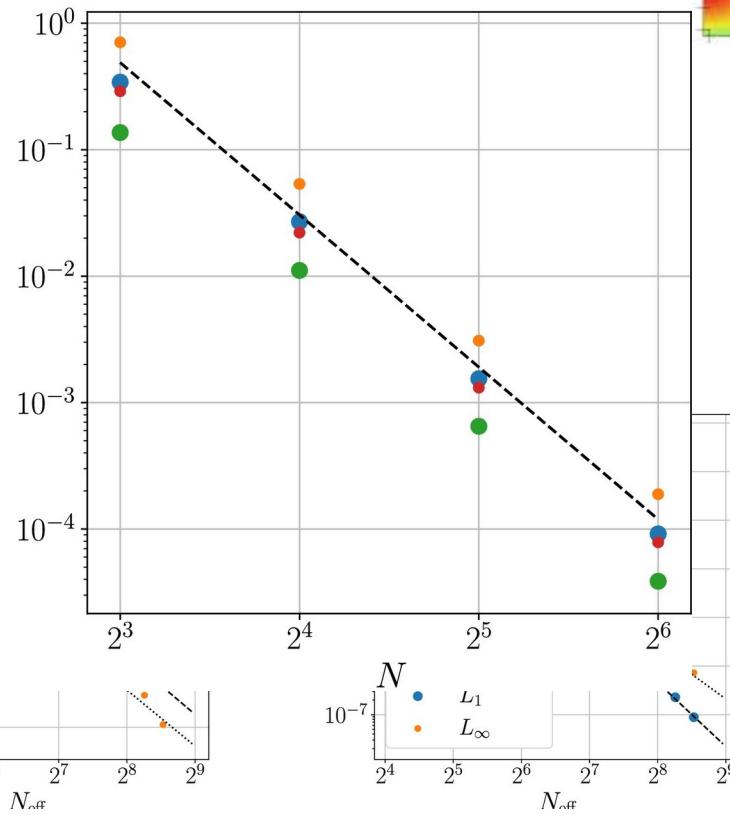
(a) Face average to vertex



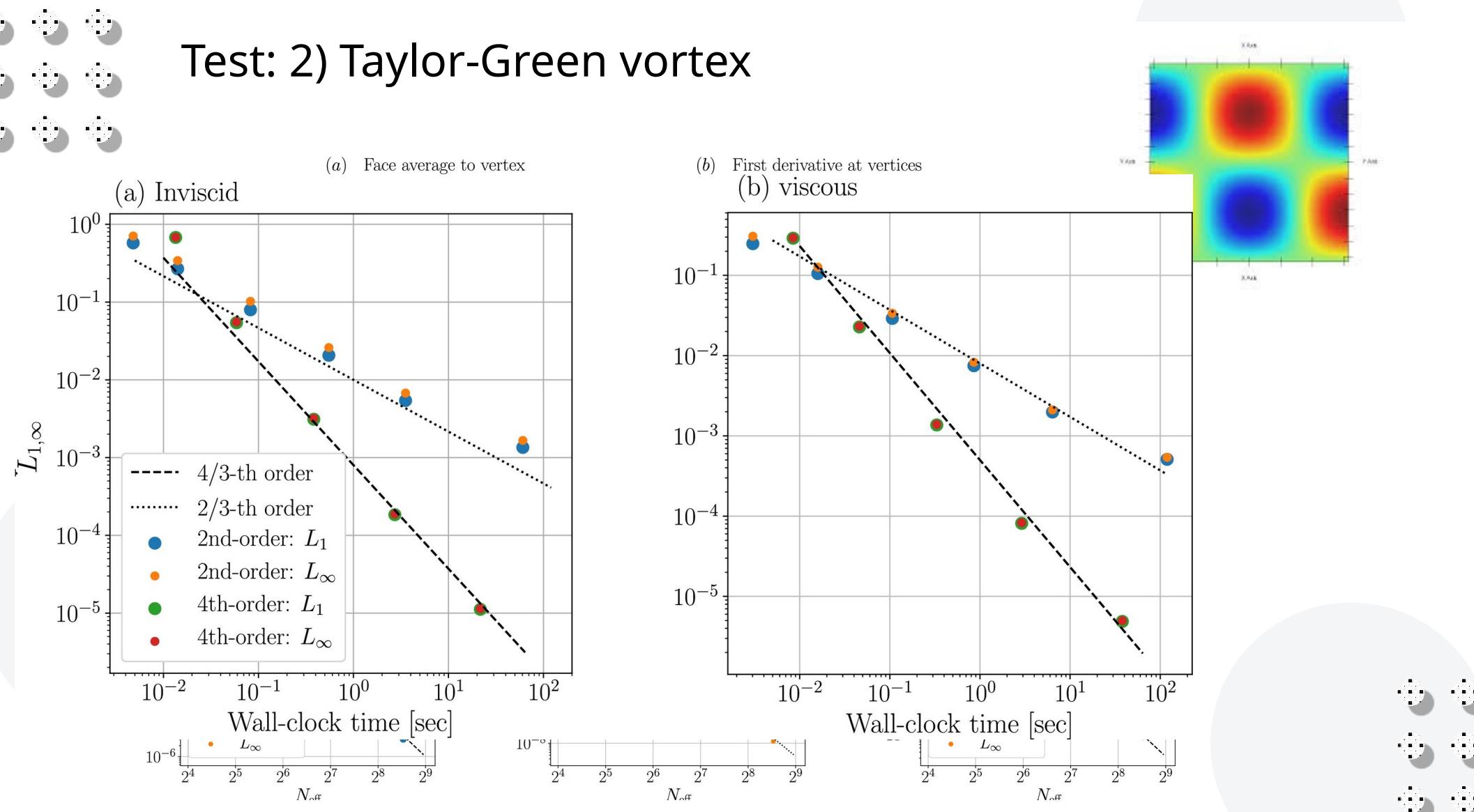
(b) First derivative at vertices



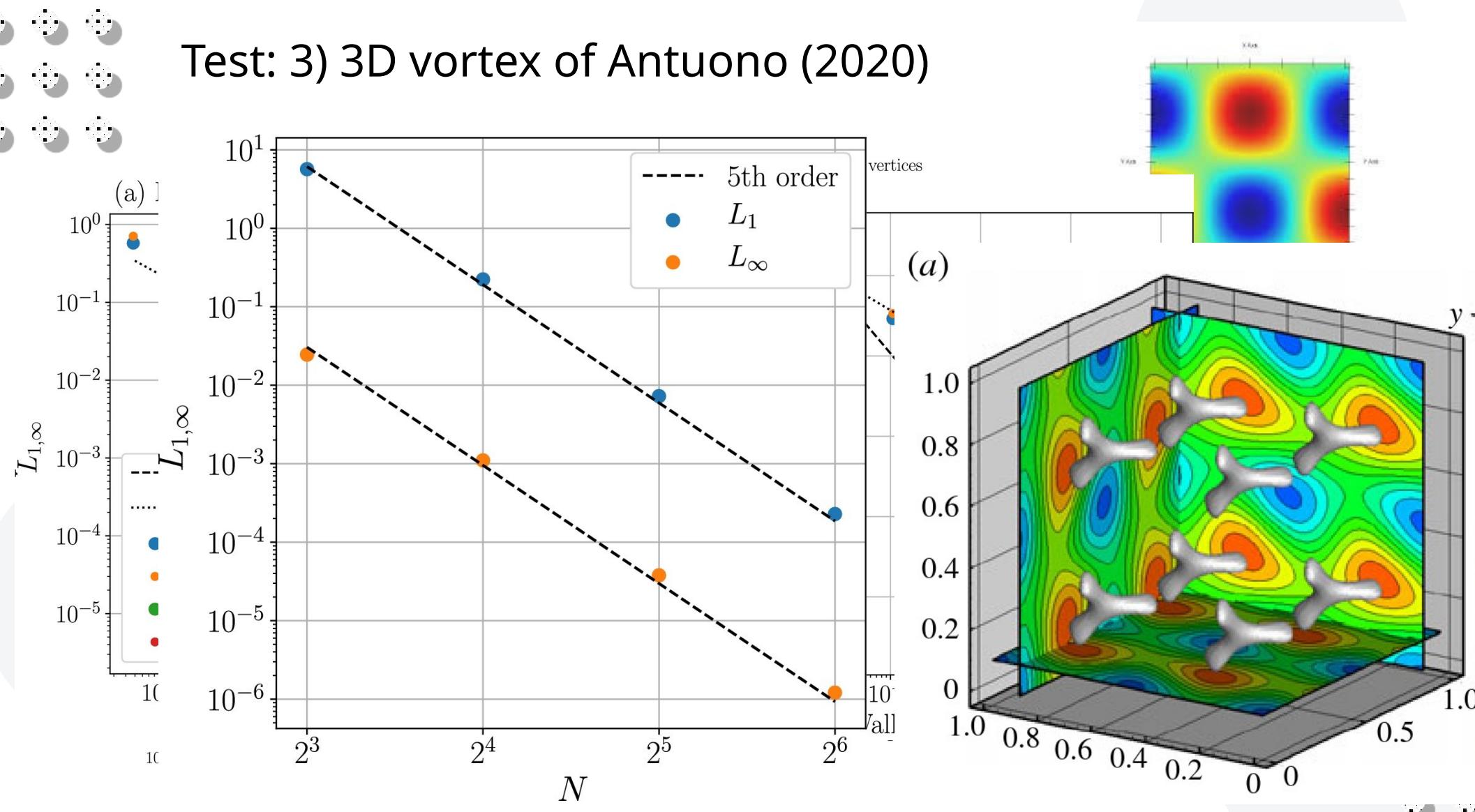
(b) $s(t = 2)$



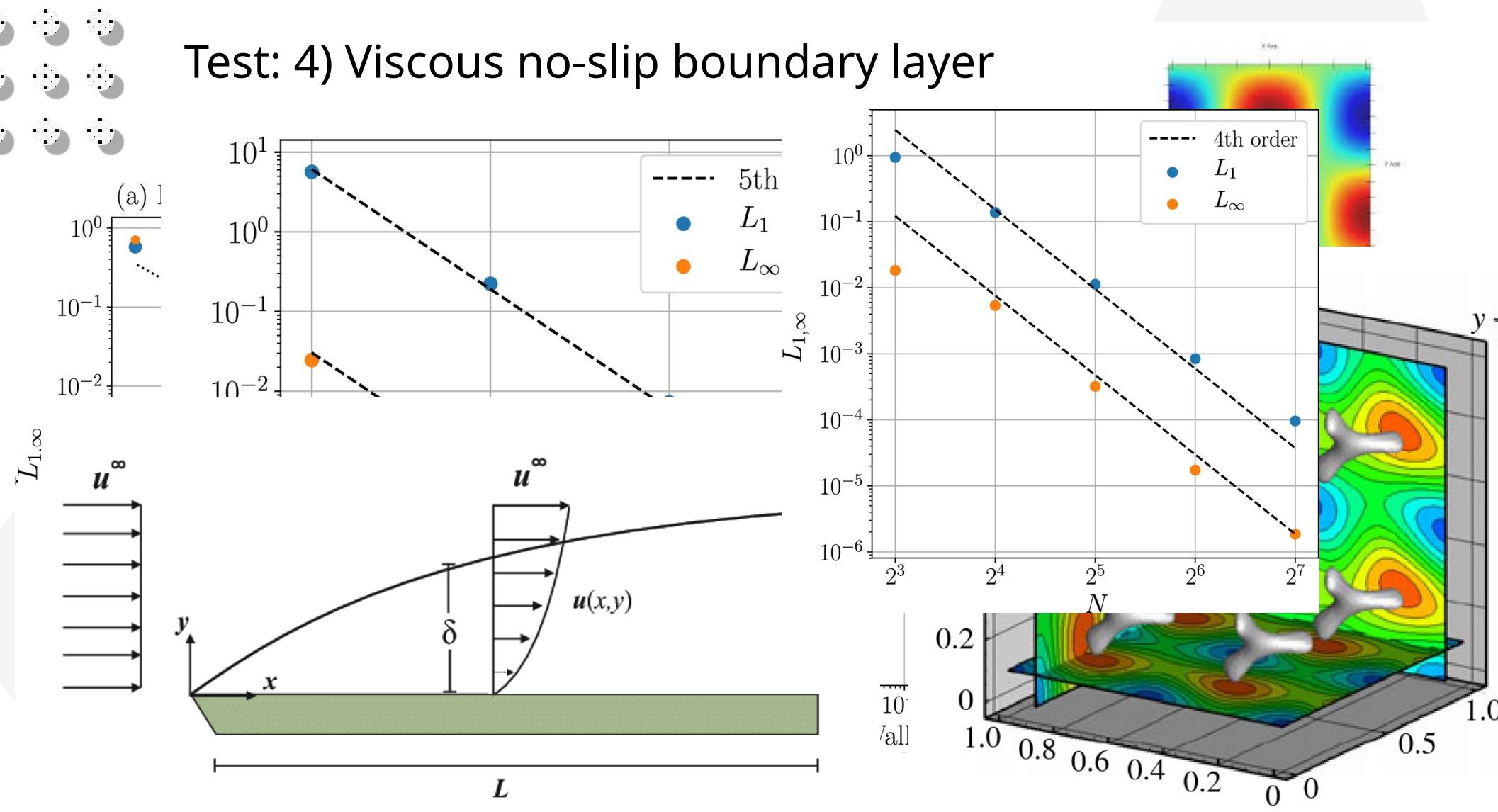
Test: 2) Taylor-Green vortex



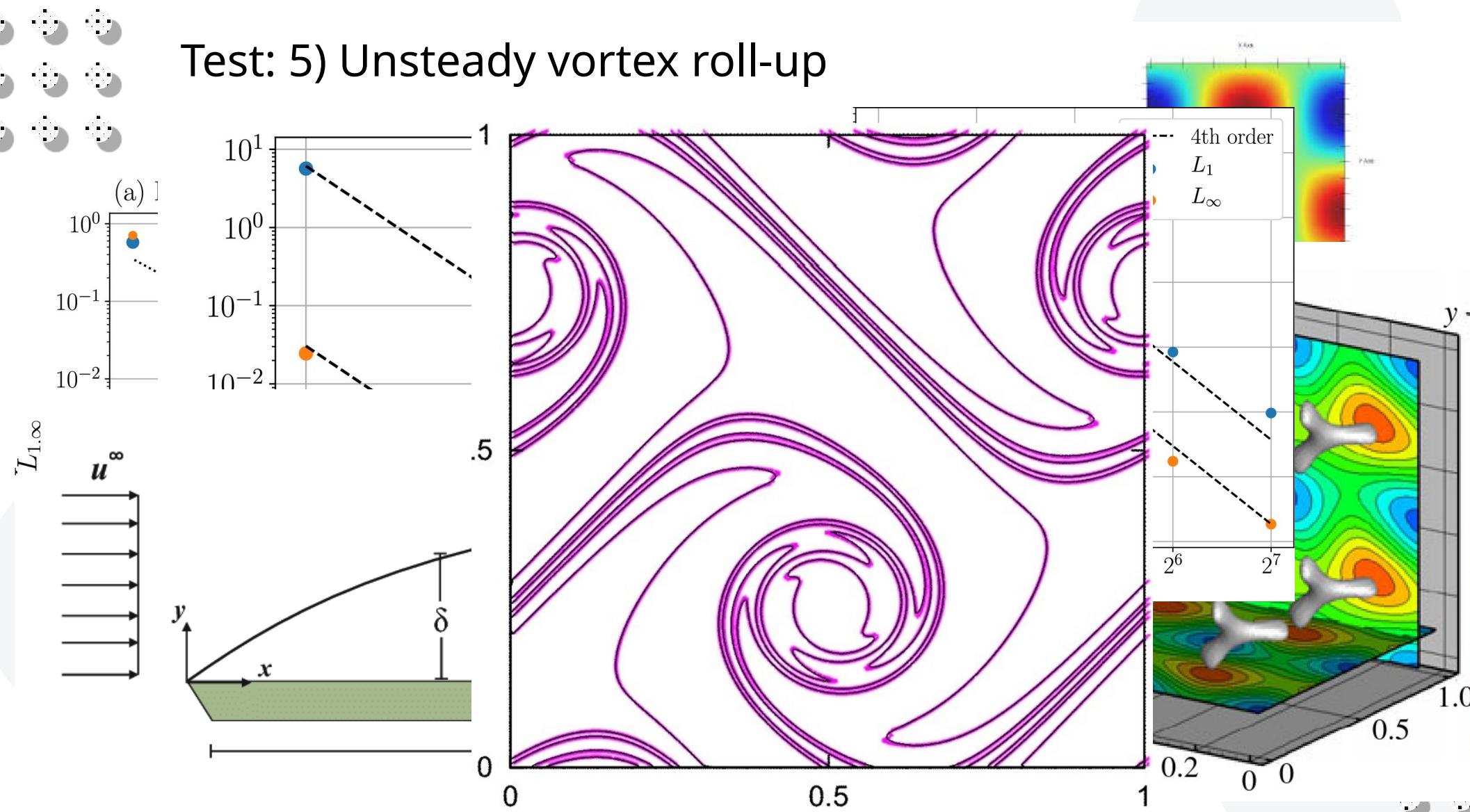
Test: 3) 3D vortex of Antuono (2020)

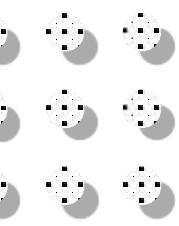


Test: 4) Viscous no-slip boundary layer

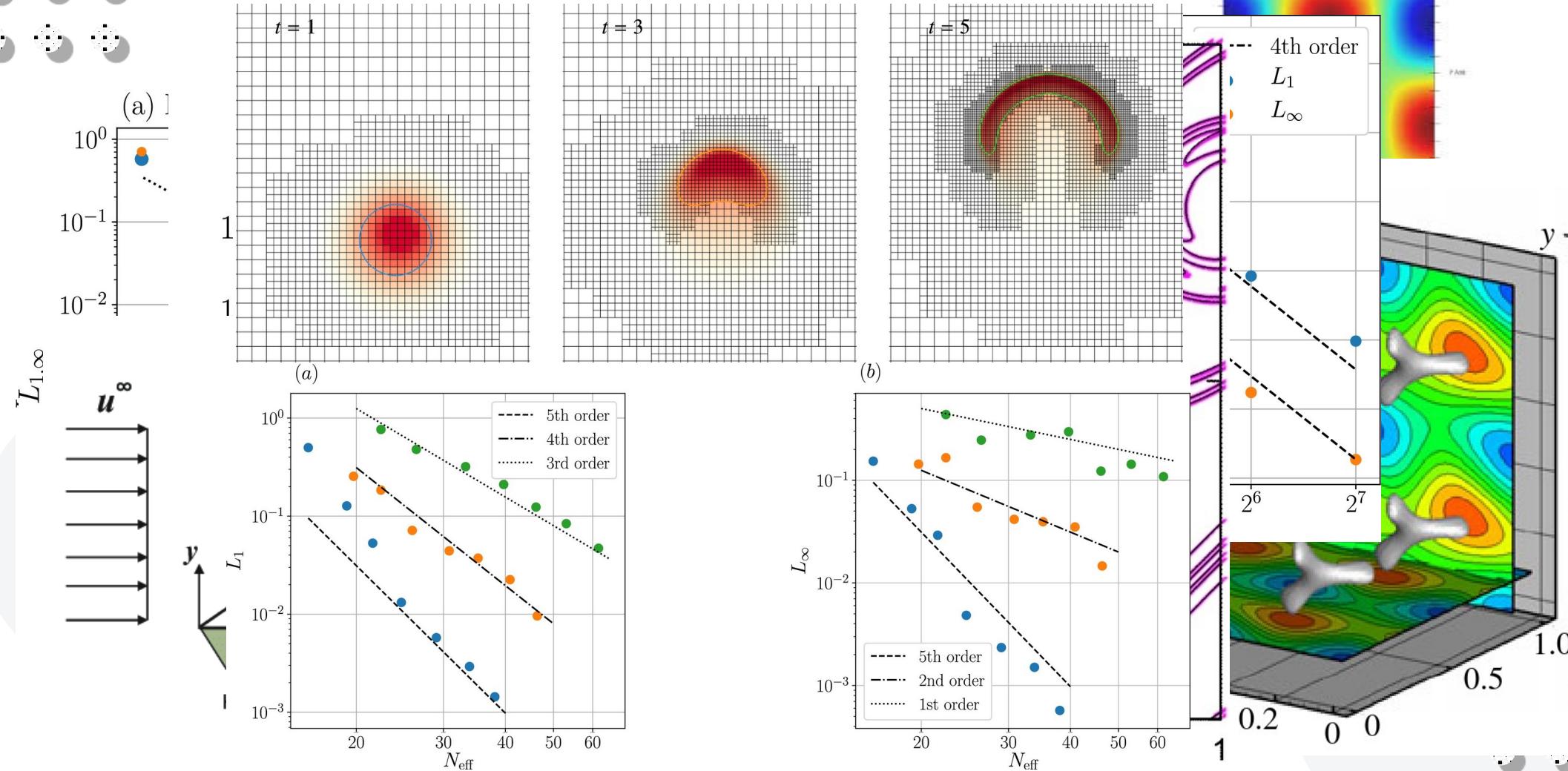


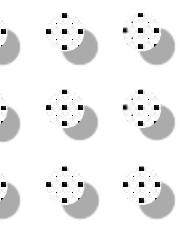
Test: 5) Unsteady vortex roll-up



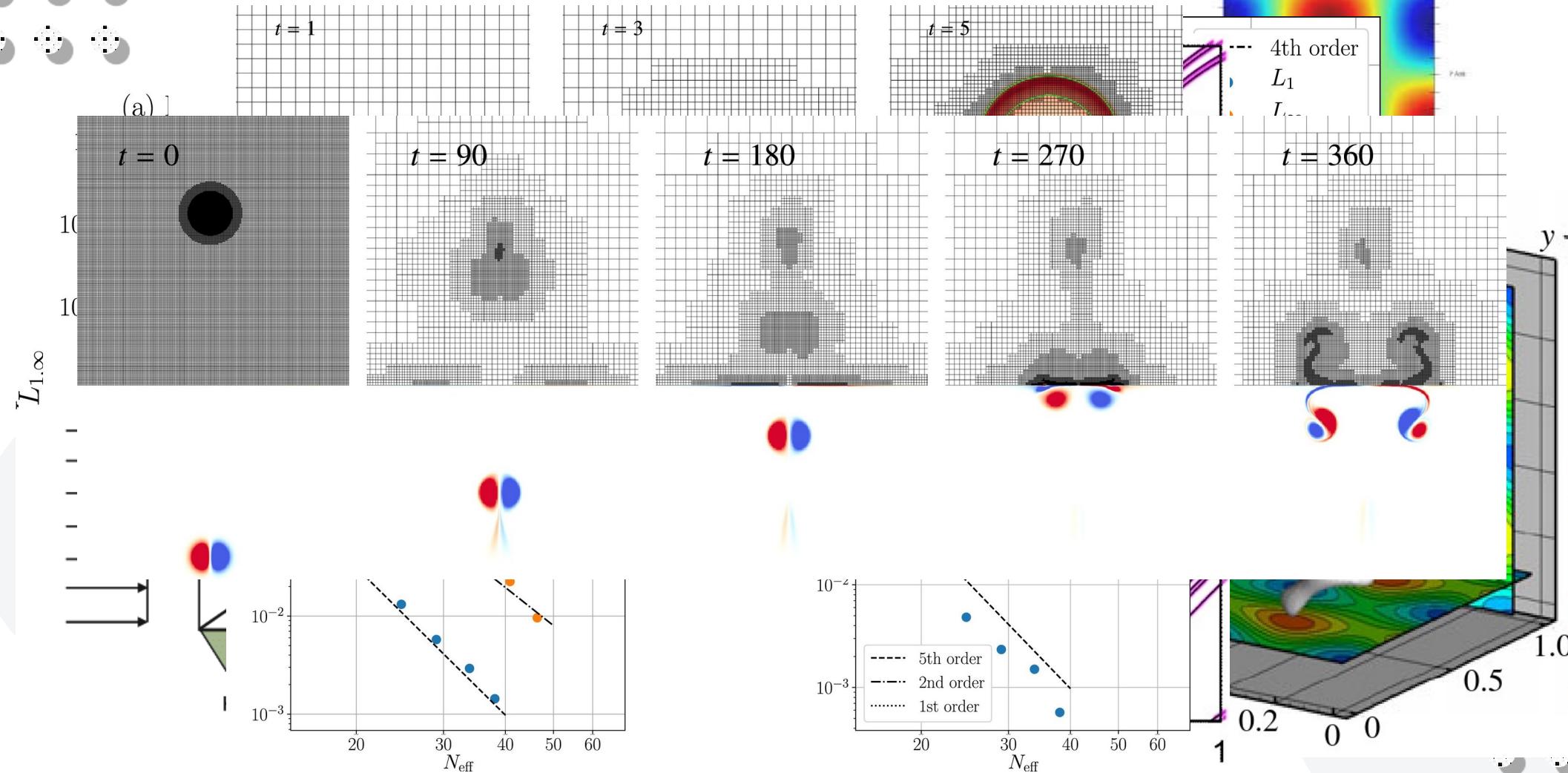


Test: 5) Rising buoyant plume





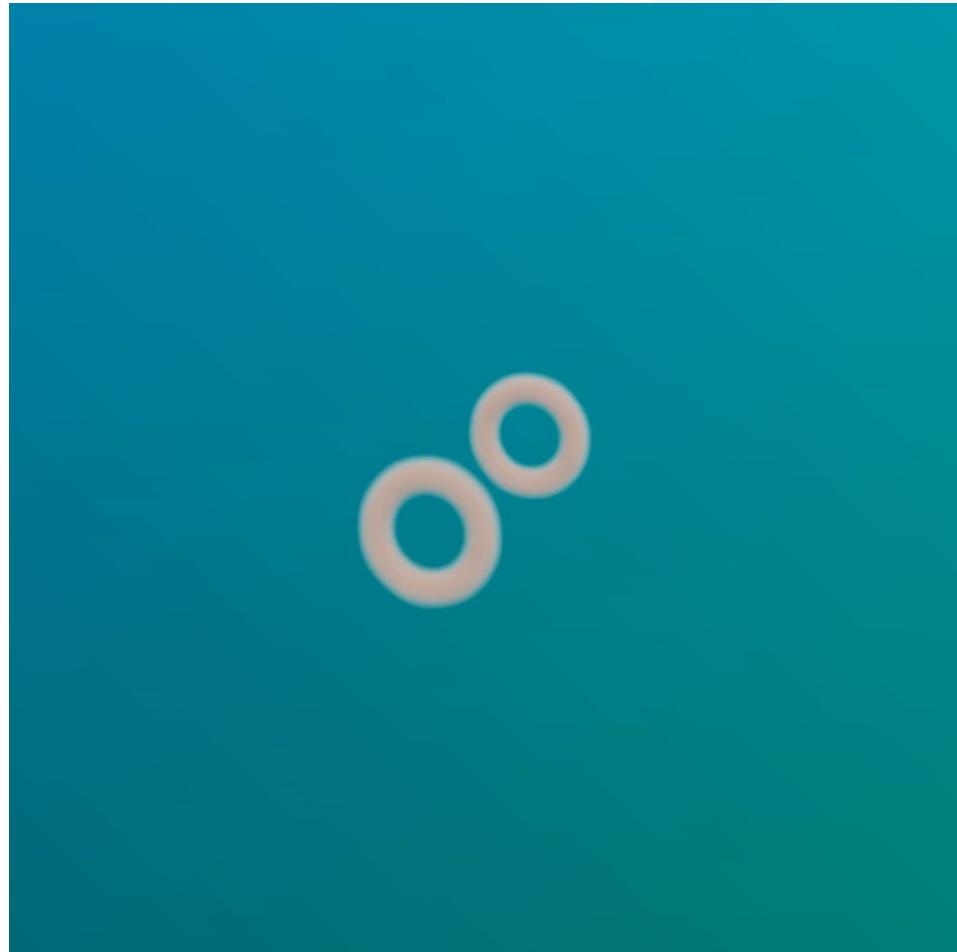
Test: 6) Vortex—Wall collision



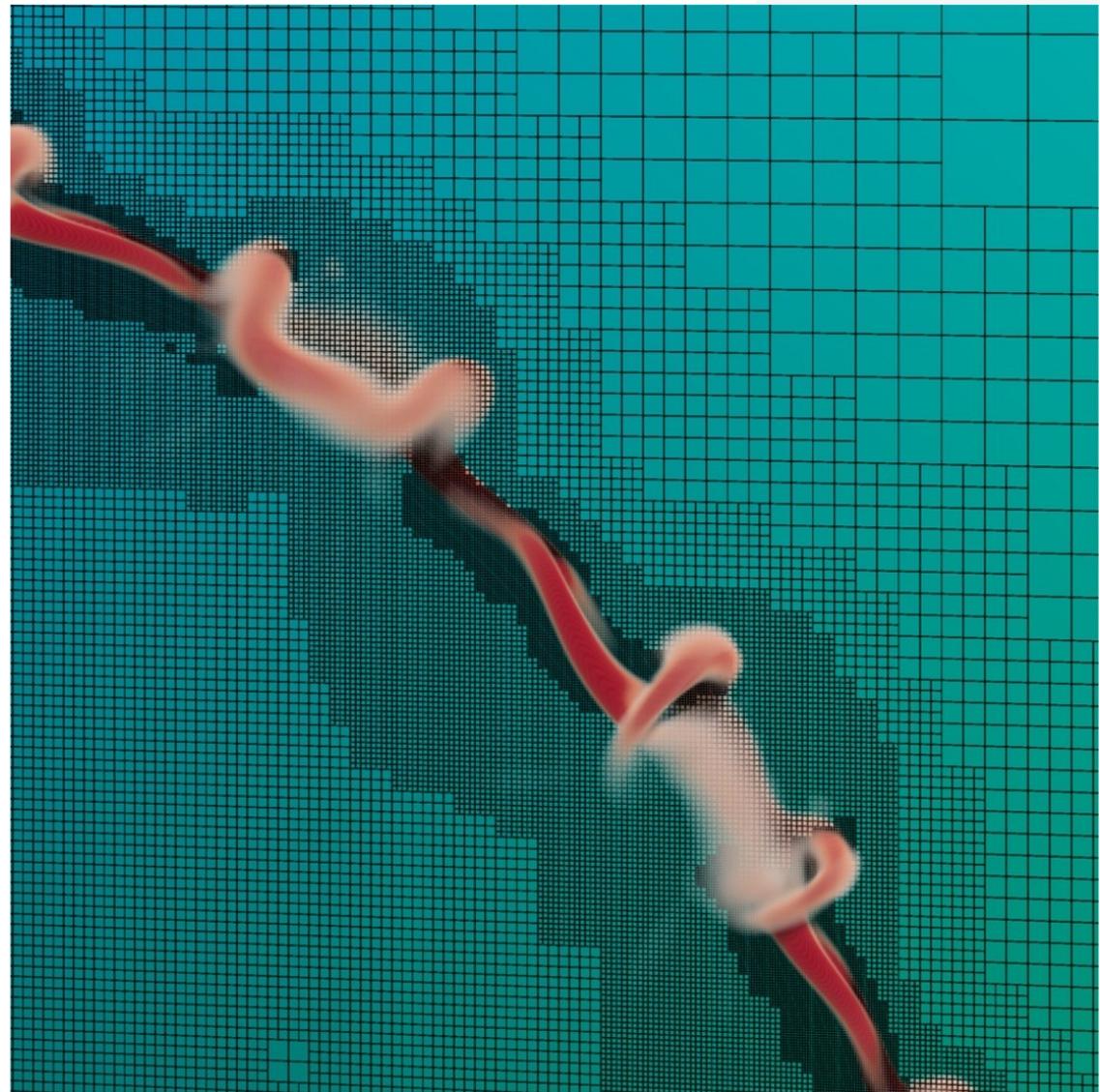
A comparison
against
'centered.h'

Movie:

www.basilisk.fr/sandbox/antoonvh/ring4.c



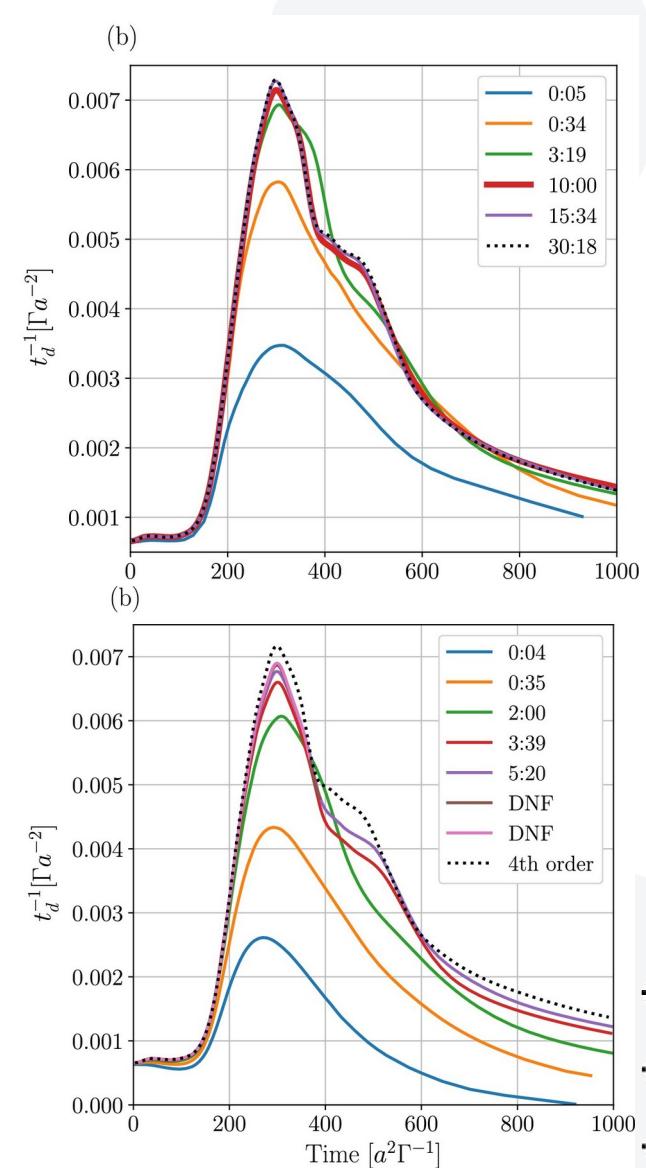
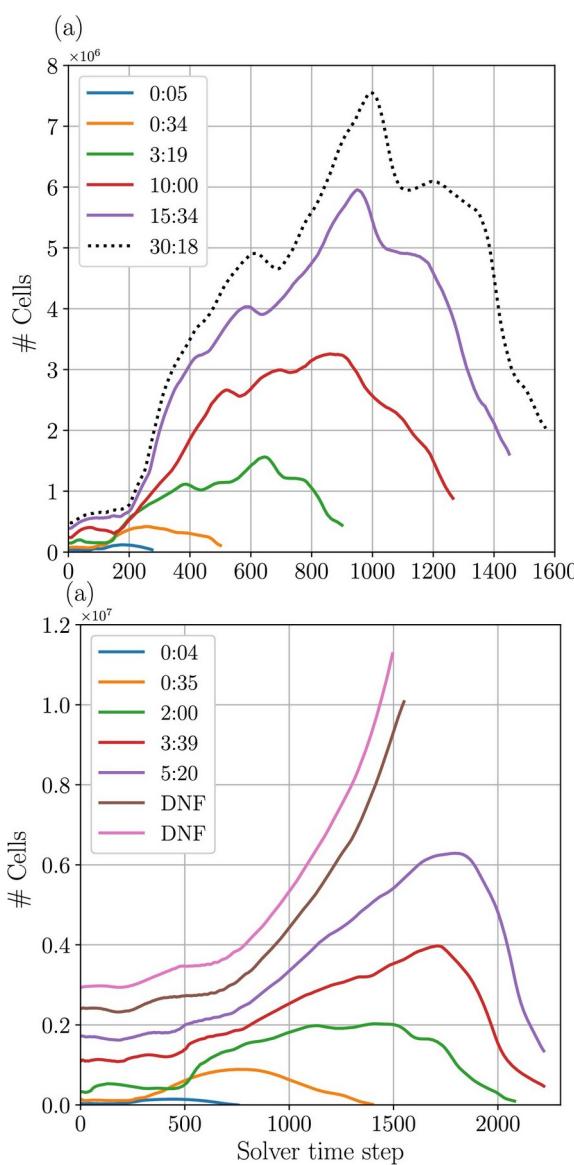
Refinement ($k = 1$)



How to converge on a tree grid?

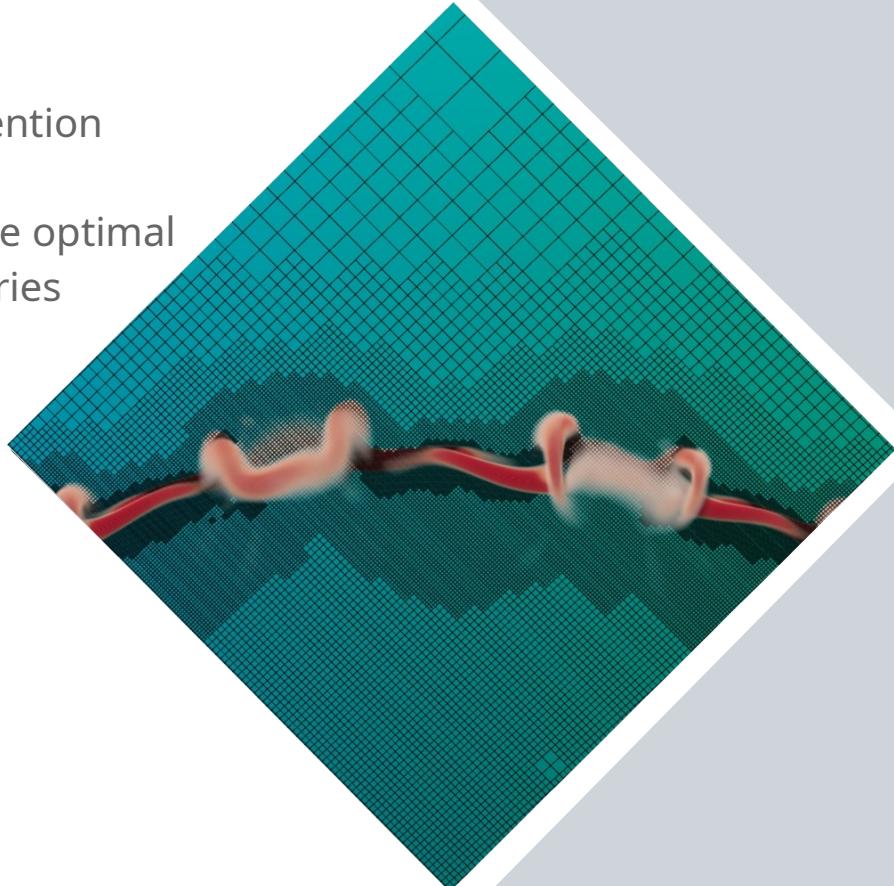
sandbox/
antoonvh/
nsf4t.h

src/
navier-stokes/
centered.h



To summarize,

1. Treatment of resolution boundaries warrants special attention
2. Wavelet-Based refinement is powerful, but not likely to be optimal when directly linked to the treatment of resolution boundaries
3. A 4th-order accurate adaptive Navier-Stokes equations solver exists for Basilisk
4. Higher-order methods can be worth the hassle



van Hooft, J. A., & Popinet, S. (2022).

A fourth-order accurate adaptive solver for incompressible flow problems.

Journal of Computational Physics, 462, 111251.

<https://www.sciencedirect.com/science/article/pii/S0021999122003138>